



Altair Radioss Explicit Solver

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Agenda

- 1. What is Radioss Explicit Solver**
- 2. Material Laws and Rupture Criteria**
- 3. Fluid Structure interaction**
- 4. Multi-Domain**
- 5. Scalability / Repeatability**
- 6. Advanced Mass Scaling**
- 7. Example: drop test on a composite glass plate**

Altair Solvers



OptiStruct

Implicit

Durability
NVH
Buckling
Thermal

RADIOSS

Explicit

Crash
Safety
Forming
Blast
FSI
Gravity
Springback

MotionSolve

Multi-Body
Dynamics

AcuSolve

CFD
Thermal

FEKO

Electro-
Magnetics

Design and Optimization

RADIOSS is a Complete Finite Element Solution in HW

Linear

Statics, Dynamics, Buckling,
Thermal, Plasticity, Quasi-static, Contact

Non-Linear (Implicit)

Quasi-static, Dynamics,
Post-buckling, Materials, Contact

Non-Linear (Explicit)

Impact, Thermal, Materials, Contact

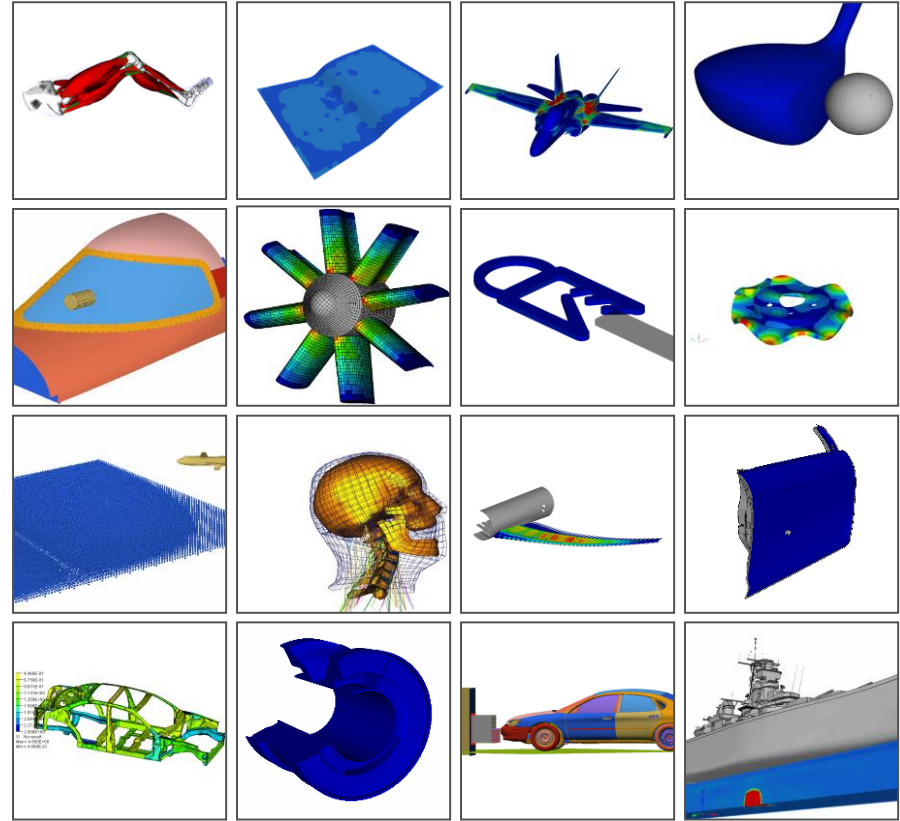
Thermal and CFD

Fluid Structure Interaction (FSI),
Thermal Stress, Multibody

Multi-Body Dynamics

(Rigid & Flexible Bodies)
Kinematics, Static and Dynamic, Quasi-static

RADIOSS



RADIOSS – used in more than 900 companies –

▪ RADIOSS in the automotive industry



RADIOSS is a Complete Finite Element Solution in HW

Access RADIOSS from HyperWorks Suite:

- Altair HyperWorks 11.0 (64-bit)
 - BatchMesher
 - HyperCrash
 - HyperGraph
 - HyperMath
 - HyperMesh Desktop
 - HyperMesh
 - HyperStudy
 - HyperView Player
 - HyperView
 - MotionSolve
 - OptiStruct
 - RADIOSS
 - AcuSolve
 - Engineering Solutions
 - HyperWorks Help
 - Manufacturing Solutions
 - solidThinking
 - Tools

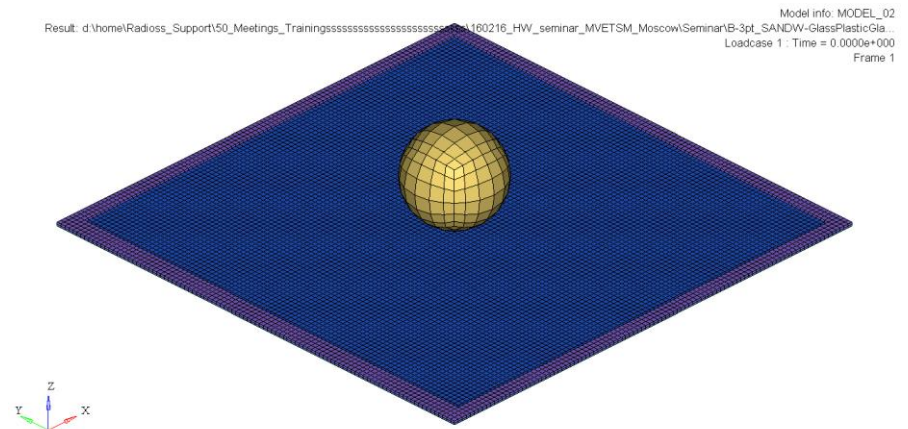
Launch RADIOSS

- HyperMath
- HyperMesh Desktop
- HyperMesh
- HyperStudy
- HyperView Player
- HyperView
- MotionSolve
- OptiStruct
- RADIOSS
- AcuSolve
- Engineering Solutions
- HyperWorks Help
 - HyperMath Solutions
 - HyperWorks Desktop
 - HyperWorks Enterprise
 - HyperWorks Introduction
 - HyperWorks Tools
 - HyperWorks Tutorials
 - Motion Solutions
 - RADIOSS, MotionSolve, and OptiStru

RADIOSS Manuals

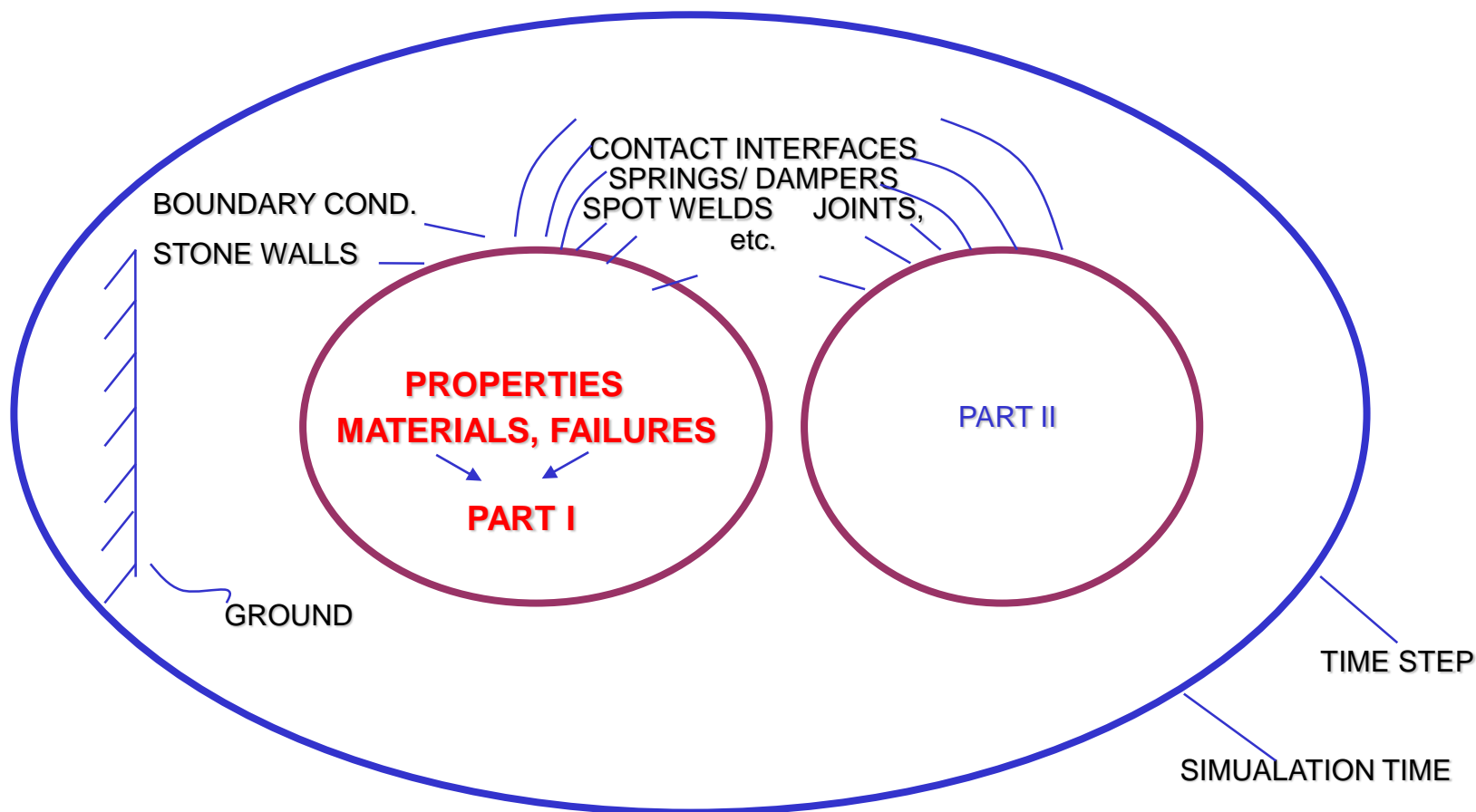
An example of problem that can be solved in Radioss

- Sphere drop (41kg) on a brittle plate (glass)
- Initial velocity of the sphere 5m/s
- The plate is composite glass and fixed on the edges
- Units: T, mm, s
- Elasto- plastic material
- Johnson Cook Failure criterion
- Crack propagation
- This problem is considered in details on seminar (data available if you need)



Structure of Radioss model

Model set up is similar to other explicit solvers



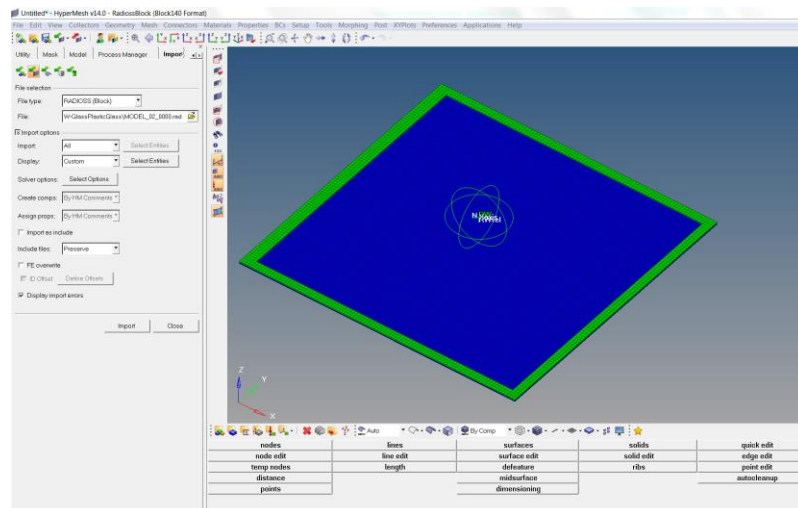
How to create Radioss model

Type ASCII file (for real experts 😊)

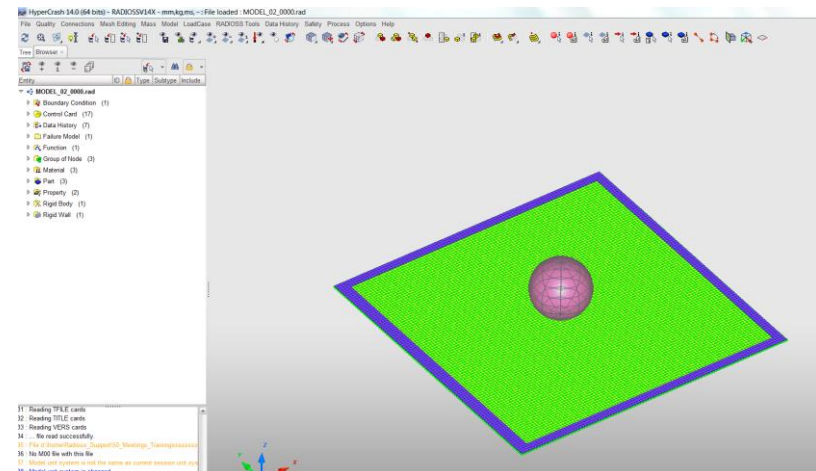
```
#RADIOSS STARTER
#---1---|---2---|---3---|---4---|---5---|---6---|---7---|---8---|---9---|---10---|
/BEGIN
model2
    140      0
           kg      mm      ms
           kg      mm      ms
#---1---|---2---|---3---|---4---|---5---|---6---|---7---|---8---|---9---|---10---|
#- 1. CONTROL CARDS:
#---1---|---2---|---3---|---4---|---5---|---6---|---7---|---8---|---9---|---10---|
/TITLE
Scaled F furnace with SPH
#---1---|---2---|---3---|---4---|---5---|---6---|---7---|---8---|---9---|---10---|

Etc.
```

Use Hypermesh



Use Hypercrash



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7. Example: drop test on a composite glass plate

Material library in Radioss

Metallic alloys

- Law 1 : elastic material
- Law 2 : elasto-plastic material
- Law 27 : elasto-plastic brittle material
- Law 36 : tabulated elasto-plastic material
- Law 60: ~ 36 + quadratic strain rate interpolation
- Law 66: Visco Elastic Plastic Piecewise Linear Material

Austenitic & stainless steels

- Law 63: Hansel material
- Law 64: Ugine & Al Z material

Crushable foams (*Honeycomb*)

- Law 28: Honeycomb
- Law 50: Crushable foam
- Law 68: Cosserat medium

Foams

- Law 33: Closed Cell visco-elasto-plastic
- Law 35: Generalized Kelvin-Voigt open/closed cells
- Law 38: Tabulated visco-elastic material
- Law 70: Tabulated hyper visco elastic material

Rubber

- Law 42: Ogden-Mooney-Rivlin
- Law 62: Hyper Visco Elastic material

Plastic

- Law 36: tabulated elasto-plastic material
- Law 65: Elastomer material
- Law 66: Visco Elastic Plastic Piecewise Linear Material
- Law 76: SAMP

Glass

- Law 27: elasto-plastic brittle material
- Law 36: tabulated elasto-plastic material

Composite

- Law 36: tabulated elasto-plastic material
- Law 15: Tsai-Wu plasticity + Chang & Chang failure
- Law 25: Tsai-Wu plasticity model

Fabric

- Law 19: linear elastic orthotropic material
- Law 58: nonlinear elastic material

Special

- Law 5: Jones Wilkins Lee Material (Explosives e.g. TNT)

+ *User defined material subroutines*

Material Law 2: simple elasto- plastic material

Material LAW2 Johnson-Cook

with rupture

- Example of Radioss card
 - Mild steel material

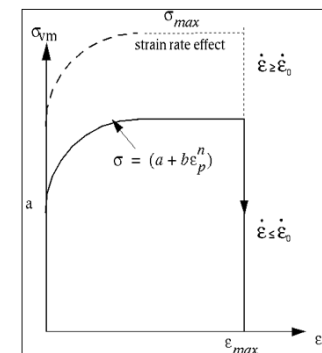
Material LAW2 (Johnson-Cook)

- Definition
 - The material law is defined using Johnson – Cook formulation :

$$\sigma = (a + b\epsilon_p^n) \left(1 + c \ln \frac{\dot{\epsilon}}{\dot{\epsilon}_0}\right) (1 - T^m)$$

plastic strain effect
strain rate effect
temperature change

- | | |
|---|---|
| <ul style="list-style-type: none"> σ = True stress level ϵ_p = True plastic strain a = Yield stress b = Hardening modulus n = Hardening Exponent | <ul style="list-style-type: none"> c = Strain rate coefficient $\dot{\epsilon}$ = Strain rate $\dot{\epsilon}_0$ = Reference strain rate |
|---|---|



```

#---1--- | ---2--- | ---3--- | ---4--- | ---5--- | ---6--- | ---7--- | ---8--- | ---9--- | ---10--- |
/MAT/PLAS_JOHNS/1
Material_A
#       Init. dens.          Ref. dens.
#           7.8E-9              0
#       E                   Nu
#       210000                .3
#       a                   b                   n                   Eps_max                   sigmax
#           400                550                .5                .4                0
#       c                   EPS0                Icc                Fsmooth                F_CUT
#           0                   0                0                0                0
#       m                   T_melt                rhoCp                T_i
#           0                   0                0                0
#---1--- | ---2--- | ---3--- | ---4--- | ---5--- | ---6--- | ---7--- | ---8--- | ---9--- | ---10--- |
    
```

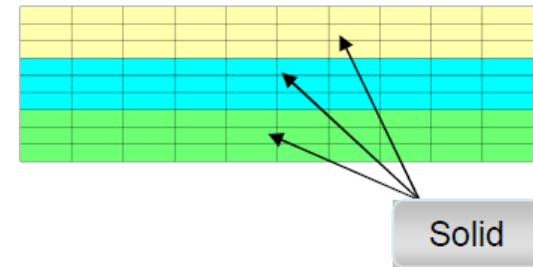
Orthotropic non-linear laminated composite material

Each ply with at least one solid

Large model, long CPU time

Advance Mass Scaling to increase simulation speed

High accuracy



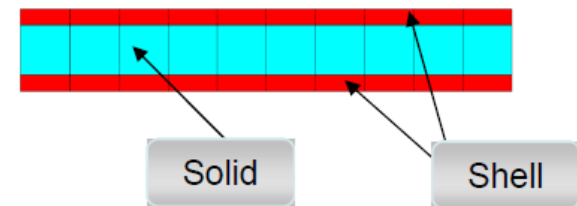
Mixed approach (middle layer thick)

Shells for top and bottom ply

Solid, thick shell or cohesive for middle layer

Several solid layers to provide rotation

Medium size model, significant CPU time



Shell & Thick shell approaches

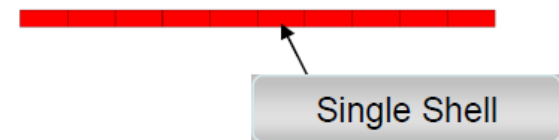
Reduced integration in normal direction

Sandwich shell approach

One shell element through the thickness

Multiple plies, with different materials

“Standard size “ model



Orthotropic non-linear composite material



Elastic

Post-Yield

```

/MAT/COMPSH/10
Altair composite material
#      RHO_I
1.5E-9      0
#      E11      E22      NU12      Iform      E33
127205      7004      .05      1
#      G12      G23      G31      EPS_f1      EPS_f2
15094      15094      15094      0      0
#      EPS_t1      EPS_m1      EPS_t2      EPS_m2      d_tens
0      0      0      0      0
#      Wpmax      Wpref      Ioff      IFLAWP      ratio
0      0      6      0      1.0
#      c      EPS_rate_0      alpha      ICC_global
0      0      0      0
#      sig_lyt      b_1t      n_1t      sig_1maxt      c_1t
1350      0      0      0      0
#      EPS_1t1      EPS_2t1      SIGMA_rst1      Wpmax_t1
0      0      0      0
#      sig_2yt      b_2t      n_2t      sig_2maxt      c_2t
66.38      0      0      0      0
#      EPS_1t2      EPS_2t2      sig_rst2      Wpmax_t2
0      0      0      0
#      sig_1yc      b_1c      n_1c      sig_1maxc      c_1c
650      .517338      .718969      0      0
#      EPS_1c1      EPS_2c1      sig_rsc1      Wpmax_c1
0      0      0      0
#      sig_2yc      b_2c      n_2c      sig_2maxc      c_2c
125      .527013      .324912      0      0
#      EPS_1c2      EPS_2c2      sig_rsc2      Wpmax_c2
0      0      0      0
#      sig_12yt      b_12t      n_12t      sig_12maxt      c_12t
0.004      67.0      0.29      0      0
#      EPS_1t12      EPS_2t12      sig_rst12      Wpmax_t12
0      0      0      0
#      GAMMA_ini      GAMMA_max      d_max
1E31      1E31      .9999
#      Fsmooth      Fcut
0      0.0
    
```



Tension in 0 degrees



Tension in 90 degrees



Tension in 45 degrees



Compression in 0 degrees

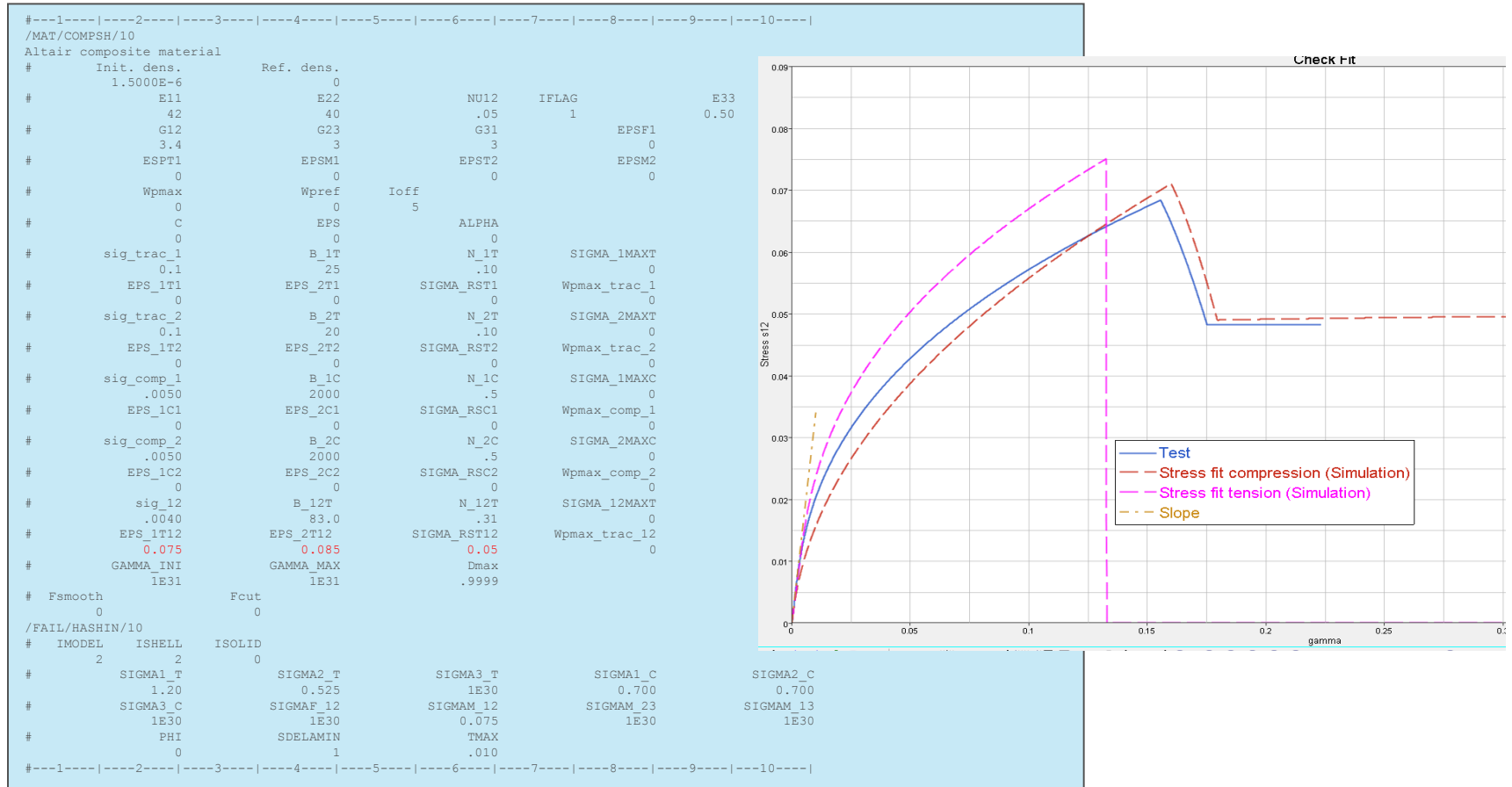


Compression in 90 degrees



Compression in 45 degrees

Example of validation for 45 deg compression

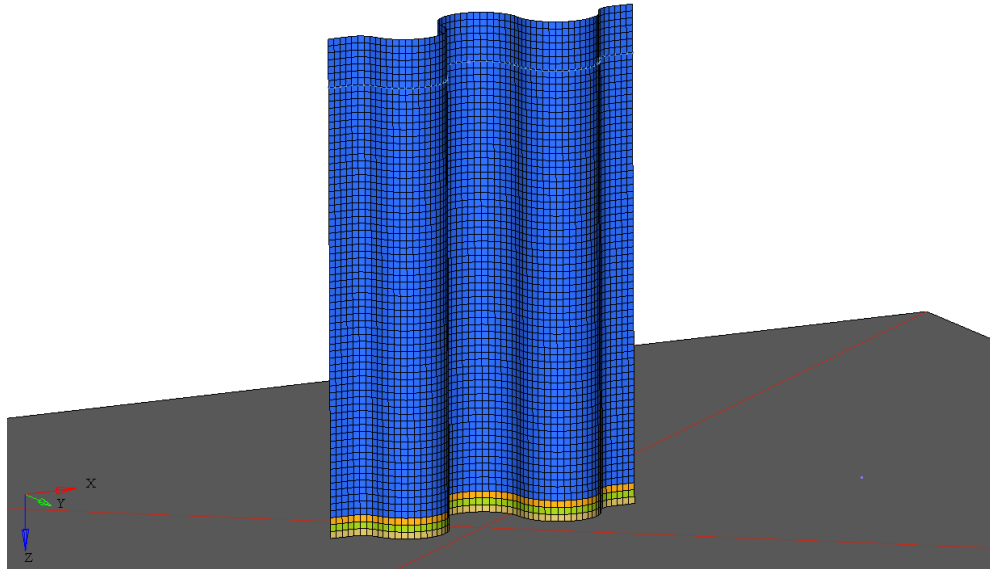


- Strains to damage and rest stress in direction 12 are used to reproduce the test behavior
- Note that damage strains are half of the damage gamma values

Sinus beam crash (generic composite material)



Model info: CMH17DLR2_001a
 Result: i:/50_Meetings_Trainingsssssssssssssssssssss/141013_Moscow_Composite_Week/Irkut/run3_stable_model_altair_material/CMH17DLR2_001aA001
 Loadcase 1 : Time = 0.0000e+000
 Frame 1



```

#- RADIOSS DECK WRITTEN BY HyperCrash
#Model4 + Interface Julien + Iol ductile
File d11 08 16:48:01 2008
#-
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
/ENGINE
CMH17DLR2_001a
120      0
      kg      mm      ms
      kg      mm      ms
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
#- 1. CONTROL CARDS:
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
/TITLE
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
/ANALY
# N2DD      IPARITH      ISUM
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
# 0          0          0
/DEF SHELL
# ISHELL      ISMSTR      ITHICK      IPLAS      ISTRAIN      I_SHRN      IDRIL
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
# 0          0          0          0          0          1          0
/DEF SOLID
# I_SOLID      ISMSTR      ISTRAIN      IFRAME
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
# 0          0          0          0
/IOFLAG
# IPR1      IOGYP      IOUFP      IOUTY      IROUY      IDROT
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
# 0          0          0          0          0          0
/RANDOM/1
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
# 1e-03      0.5
#- 2. MATERIALS:
#-----1-----2-----3-----4-----5-----6-----7-----8-----9-----10-----
/MAT/COMP8/1
Altair composite material
#
RHO_1      1.5E-6      0
# E11      E22      NU12      Iform      E33
# 42      40      G31      1
# G12      G23      EPS_f1      EPS_f2
# 3.4      3      0      0
# EPS_r1      EPS_m1      EPS_r2      EPS_m2      d_tens
# 0      0      0      0      .9999
# Wpmax      Wpref      Ioff      IPIAMP
    
```

- Check model built up
- Definition of materials, properties
- Run settings
- Post processing

RADIOSS – Rupture Criteria

Failure Model Description

Failure Model Keyword	Type	Description
CHANG	Chang-Chang model	Failure criteria for composites
CONNECT	Failure	Normal and Tangential failure model
ENERGY	Energy isotrop	Specific energy

MATERIAL MODELS & RUPTURE CRITERIA LIBRARIES
=>
MORE THAN 300 COMBINATIONS

TBUTCHER	Tuler-Butcher model	Failure due to fatigue
TENSSTRAIN	Traction	Strain failure
USERi	User failure model	
WIERZBICKI	Ductile material	Bao-Xue-Wierzbicki model
WILKINS	Ductile failure model	Wilkins model
XFEM_FLD	Forming limit diagram	Fld
XFEM_JOHNS	Ductile failure model	Johnson-Cook
XFEM_TBUTC	Ductile (brittle) failure model	Modified Tuler-Butcher model
EMC	Ductile material	Extended Mohr-Coulomb MIT

Tabulated failure criterion for elastoplastic materials

- Failure Curve (eps_f vs. triaxiality) test – input is a user function
- Strain Rate Dependency – Different curves for different strain rates
- Element Length Dependency
- Load path is taken into account by damage accumulation
- Bending Behavior: Percentage of Thickness to fail before deleting shells

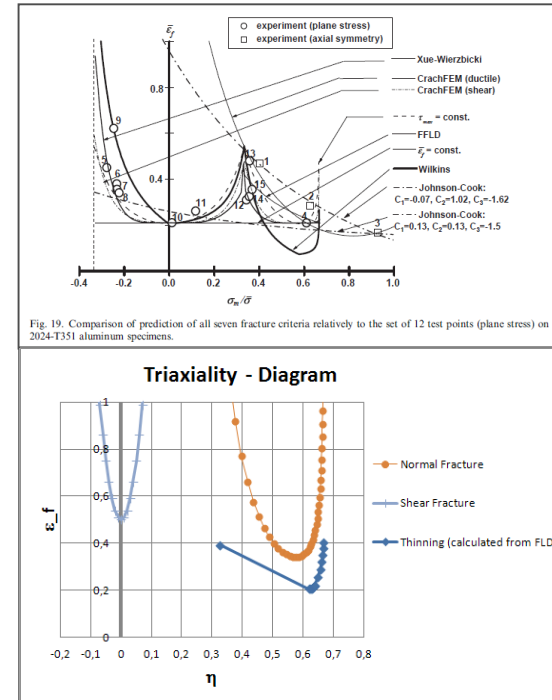
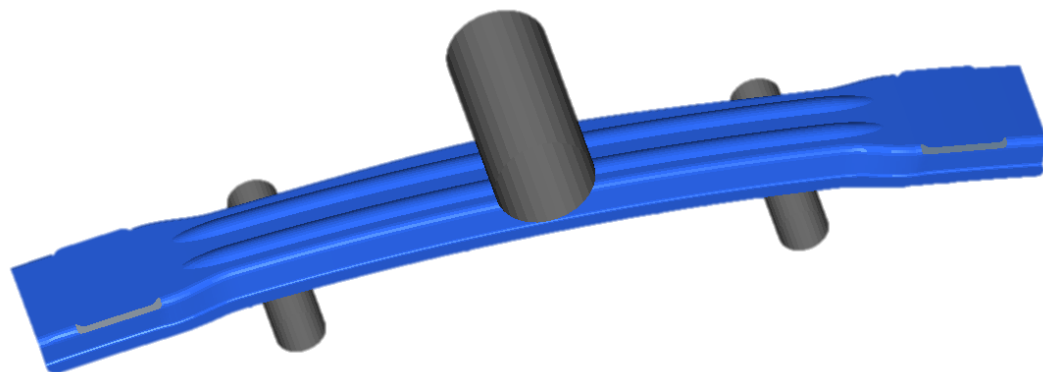


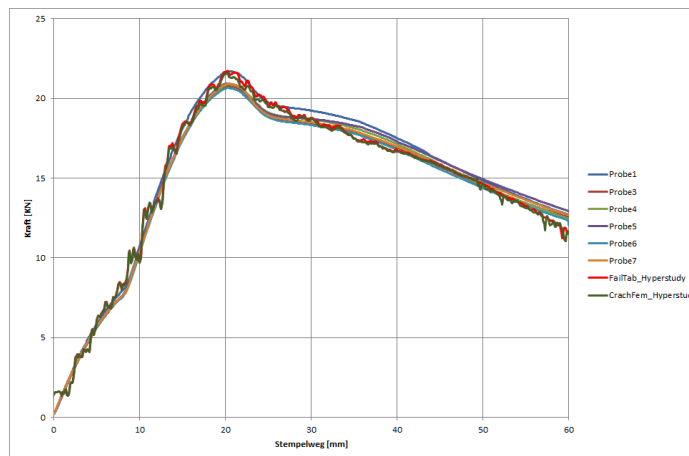
Fig. 19. Comparison of prediction of all seven fracture criteria relative to the set of 12 test points (plane stress) on 2024-T351 aluminum specimens.



Tabulated failure criterion for elastoplastic materials



RADIOSS simulation



Simple Chang-Chang failure criteria for composites

■ With fiber direction 1:

- Tensile fiber mode:

$$\left(\frac{\sigma_{11}}{S_1}\right)^2 + \beta \left(\frac{\sigma_{12}}{S_{12}}\right)^2 \geq 1 \quad \sigma_{11} > 0$$

0 deg Tension
45 deg Tension

- Compressive fiber mode:

$$\left(\frac{\sigma_{11}}{C_1}\right)^2 > 1 \quad \sigma_{11} < 0$$

0 deg Compression

■ For matrix cracking:

- Tensile matrix mode

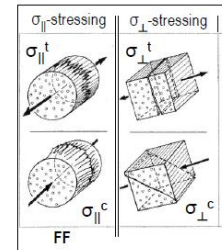
$$\left(\frac{\sigma_{22}}{S_2}\right)^2 + \beta \left(\frac{\sigma_{12}}{S_{12}}\right)^2 > 1 \quad \sigma_{22} > 0$$

90 deg Tension
45 deg Tension

- Compressive matrix mode

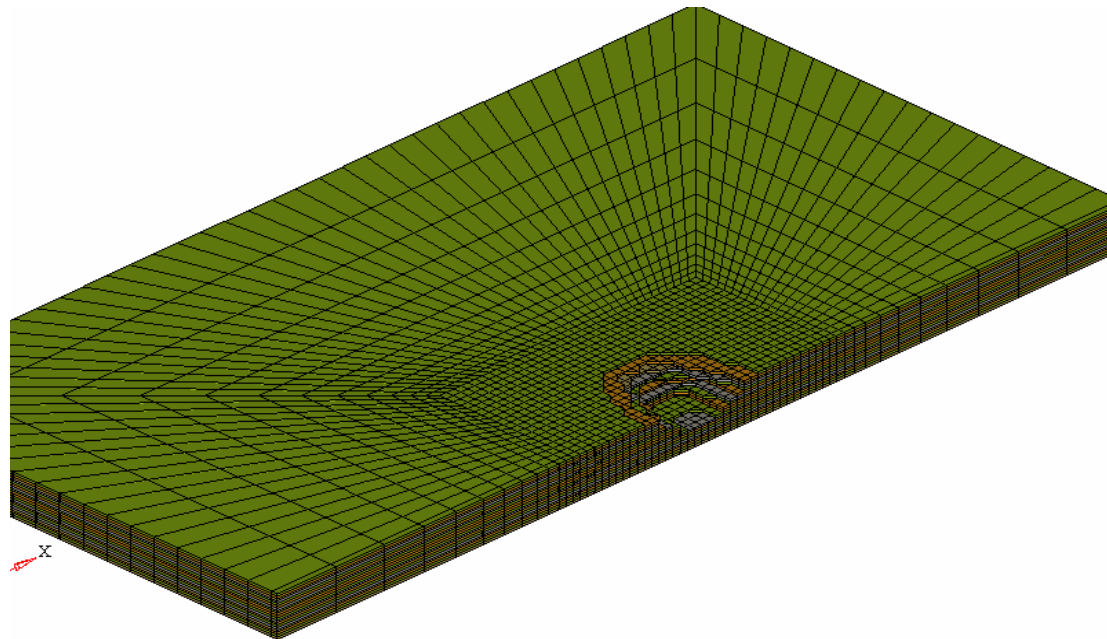
$$\left(\frac{\sigma_{22}}{2S_{12}}\right)^2 + \left[\left(\frac{C_2}{2S_{12}}\right)^2 - 1\right] \frac{\sigma_{22}}{C_2} + \left(\frac{\sigma_{12}}{S_{12}}\right)^2 > 1 \quad \sigma_{22} < 0$$

90 deg Compression
45 deg Compression

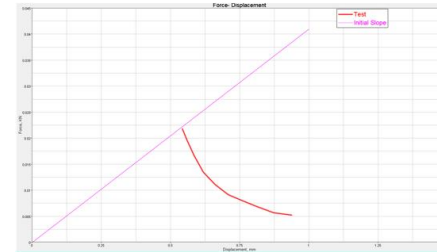
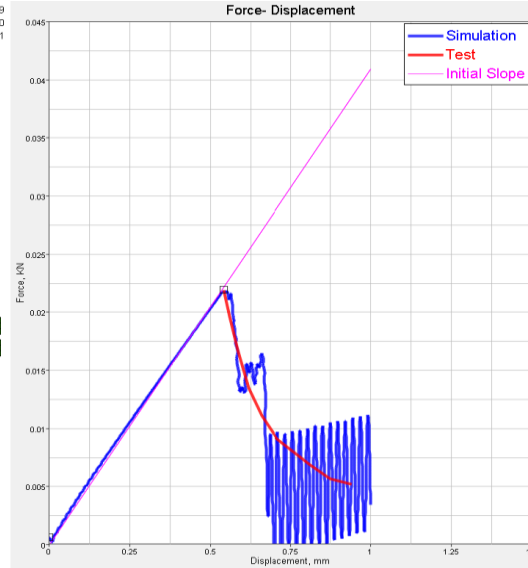
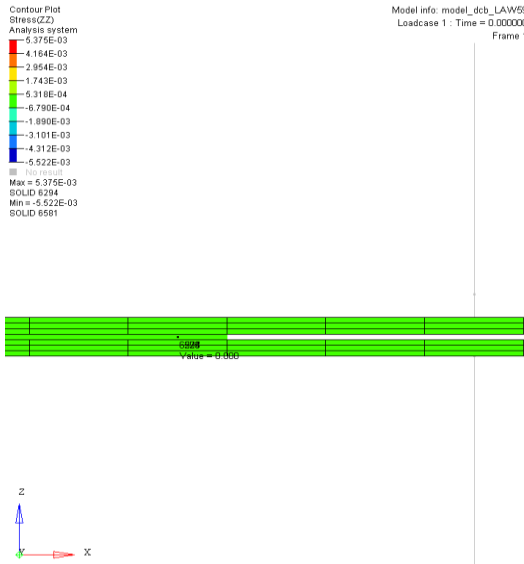


Failure criteria can be combined

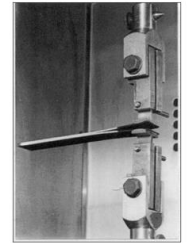
- Possibility to apply several failure criteria for one material law :
 - Example :
 - Hashin for fiber
 - Puck for Matrix
 - Ladeveze for delamination



Connect material LAW59 for adhesive layers



Pre-crack area Crack development



- Typical test curve, which shows force as function of the force transducer displacement . Normally it is shown only in crack area. Before the crack the force displacement curve is assumed to be linear
- In present case crack start at appr 0.5mm half opening (always check in the test whether the displacement is the motion of the force transducer or it is distance between upper and lower transducers)

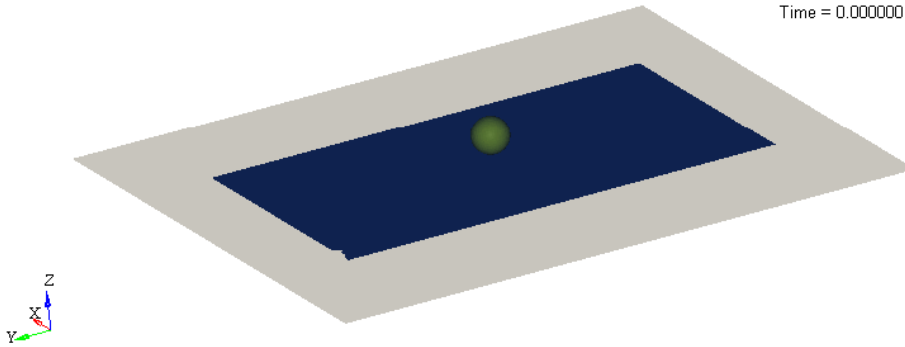
- For adhesive layers, spotwelds, any other type connections
- Element height does no affect time step. Can be 0!
- Example of DCB test with LAW59

Ply-XFEM Approach for delamination

Bvid impact on a composite plate

Shell view

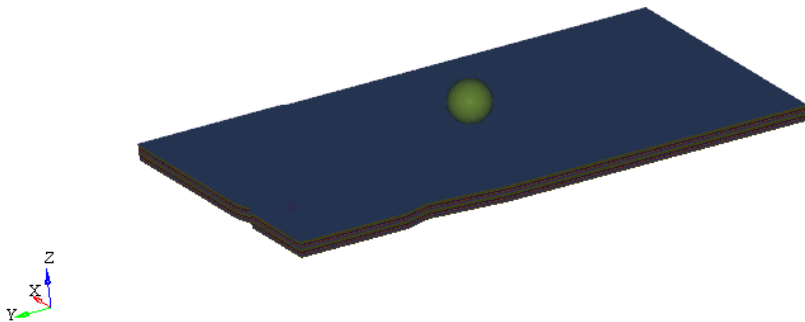
Time = 0.000000



Bvid impact on a composite plate

Plyxfem view

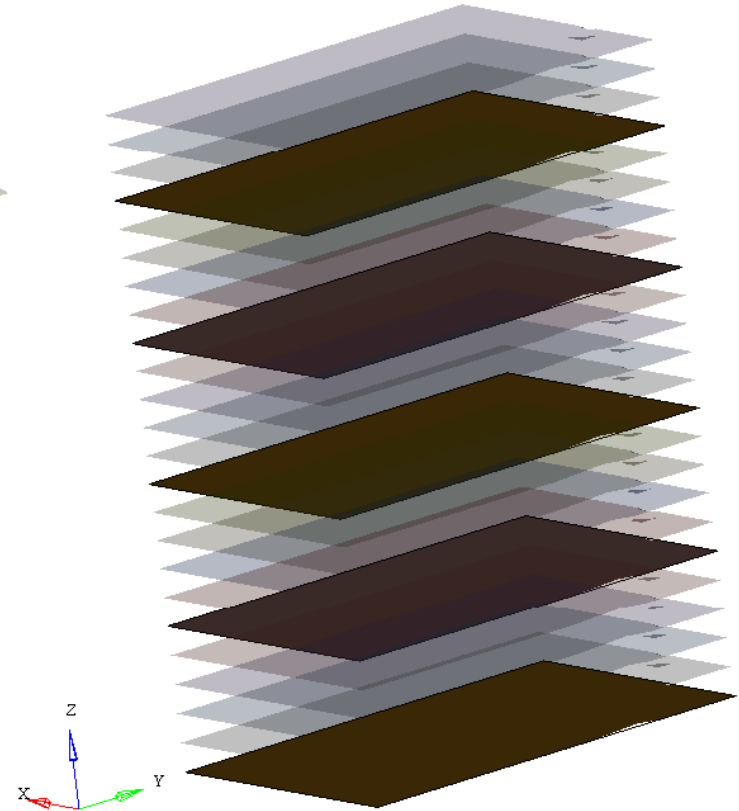
Time = 0.000000



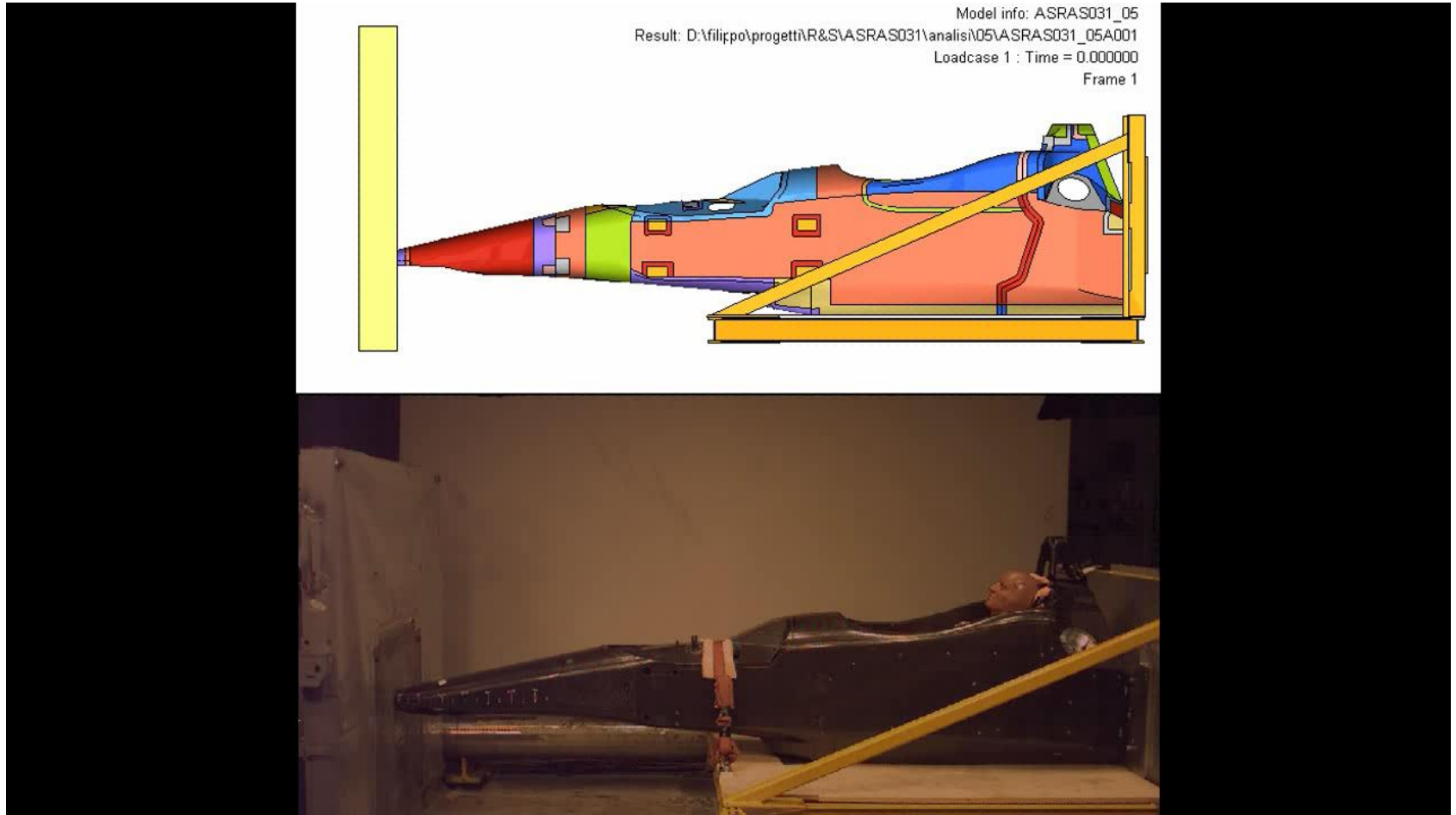
Bvid impact on a composite plate

Exploded view

Time = 0.000000



RADIOSS - DALLARA Race cars design Composite structures



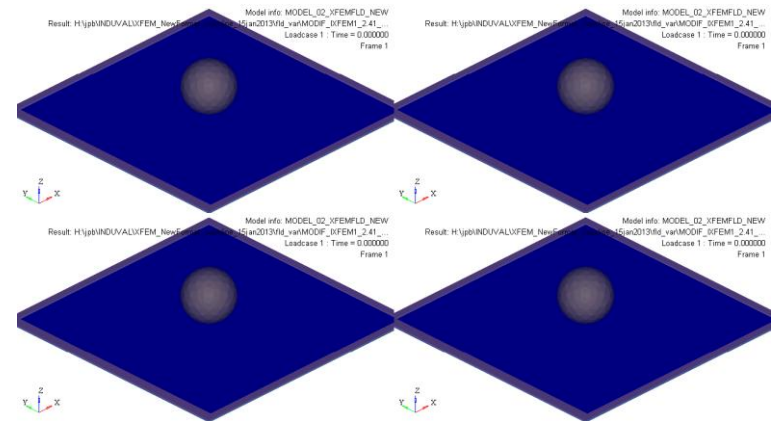
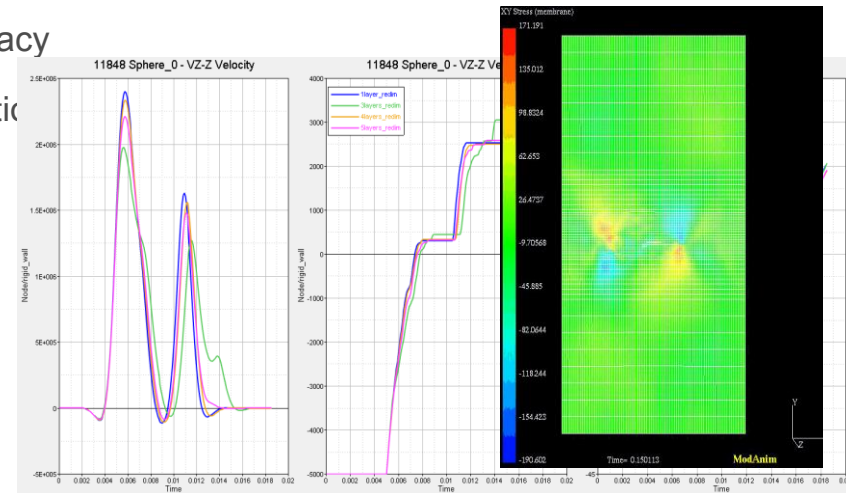
RADIOSS - X-FEM

Goals

- Splitting elements when failure occurs => ↑ accuracy
- Crack propagation independent of the mesh direction
- ↑ mesh size independency
- Allow relatively coarse mesh

Capabilities

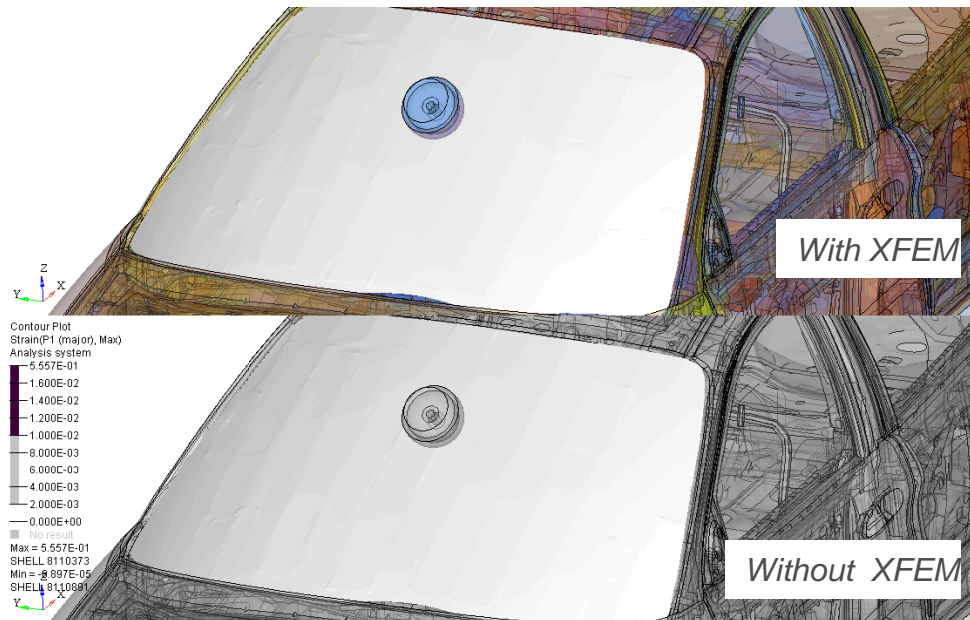
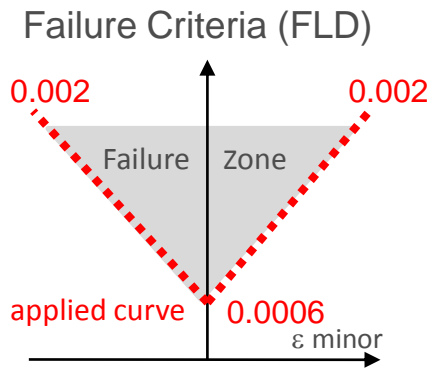
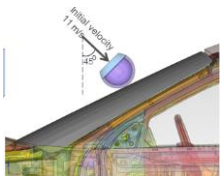
- Compatible properties
 - /PROP/SHELL isotropic mono-layer
 - /PROP/SH_SANDW isotropic/orthotropic multi-layer
- Compatible failure models
 - /FAIL/JOHNSON
 - /FAIL/TBUTCHER
 - /FAIL/TAB1
 - /FAIL/FLD
 - FAIL/TAB with Lode angle
 - /FAIL/SNCONNECT
 - /FAIL/NXT
- Crack visualization per layer
- Simple activation through the flag `lxfem = 1`



RADIOSS - X-FEM update

- Latest enhancements

- Addition of an optional “advancement parameter” [0 , 1] in all X-FEM compatible failure models
 - Decoupling of the crack initiation and the crack advancement criteria
 - Enabling the control of cracks number and crack propagation velocity
- SPMD & H-MPP compatibility and performance optimization
- Compatibility /MAT/HILL (LAW32) &/MAT/HILL_TAB (LAW43) with /FAIL/JOHNSON criterion



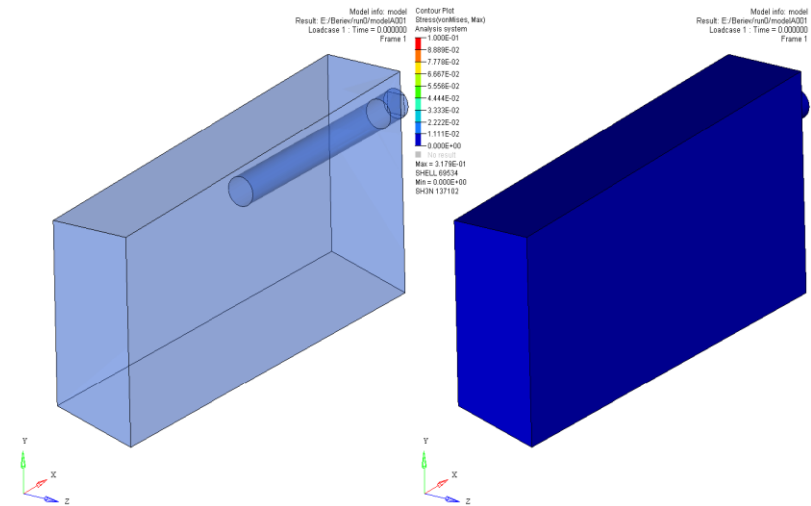
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RADIOSS FSI: SPH and ALE

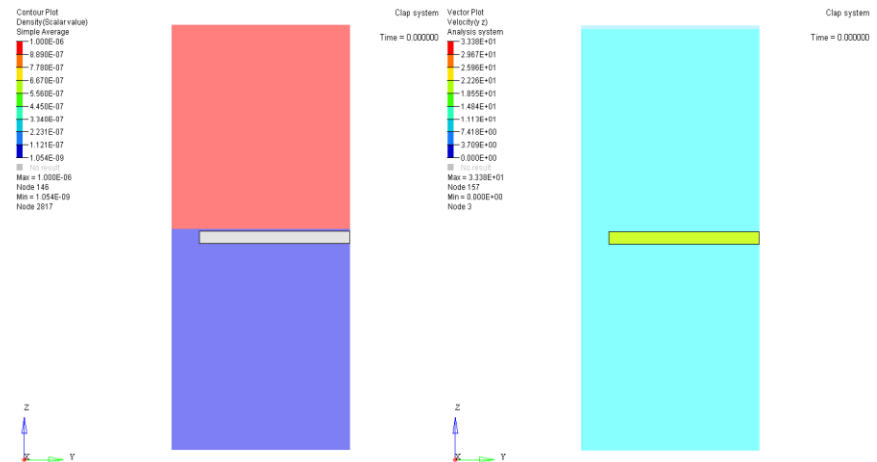
- **Smooth Particle Hydrodynamic is used :**

1. the fluid fills only a small portion of the domain
2. Air behavior can be neglected (no cavitation ...)



- **Arbitrary Lagrangian Eulerian is recommended:**

1. the fluid fills most of the domain
2. Air behavior cannot be neglected (no cavitation ...)
3. Accurate fluid modeling (turbulence ...) required



Landing run over a wavy water surface



BEREV
Numerical Experiment Ltd.
Altair

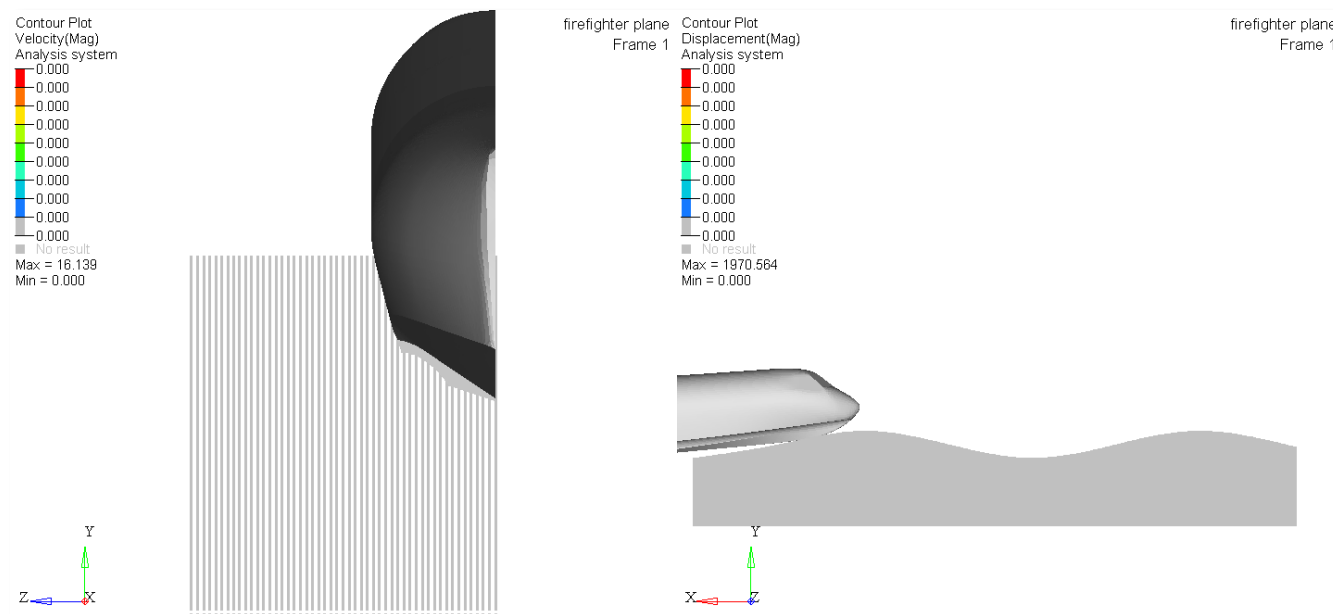
Simulation of a seaplane landing on a rough water surface using the RADIOSS multidomain method

European ATC 2015, Paris
01.10.15

Ivanov K. (Numerical Experiment Ltd., Director, Russia)
Kleptsov V. (Berev Aircraft Company, Head of Fatigue Department, Russia)
Fokin D. (Altair Inc., Senior Application Specialist, Germany)

Simulator:

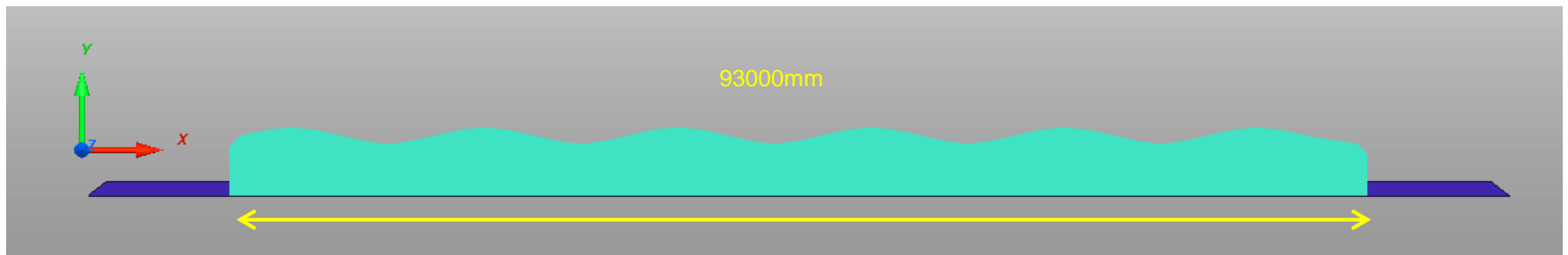
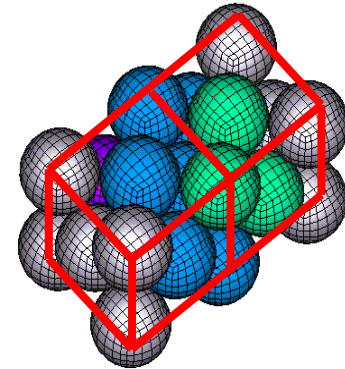
- 180kmh run along 80m water basin



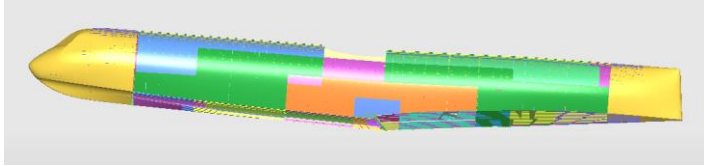
Smooth Particles Hydrodynamics for ditching problems



- Domain divided by a set of particles tied to their neighbors by internal forces
- Incompressible water material is used
- Appr 3.300.000 particles



SPH for Multidomain in Radioss



Structural domain:

- deformable structure of aircraft
- 300.000 elements
- Maximal possible time step $0.25e-02ms$



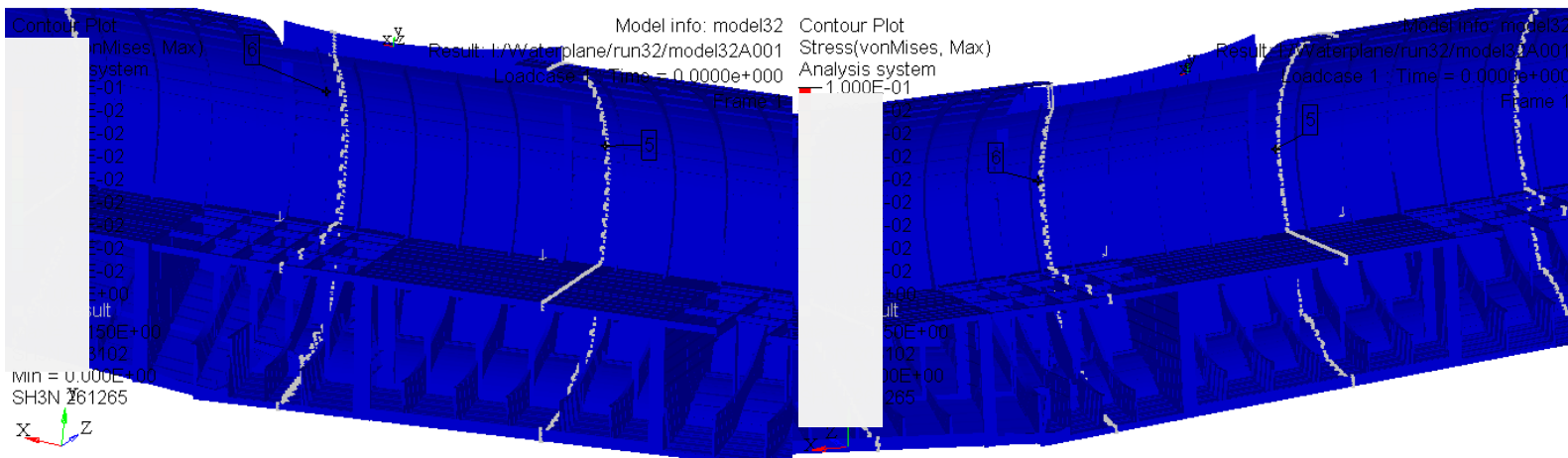
Water domain:

- SPH and void component to replicate fuselage
- type 7 contact between the void and SPH water
- Maximal time step 3.300.000 elements, maximal time step $0.17e-01ms$

180kmh. Von Mises Stress distribution in structure

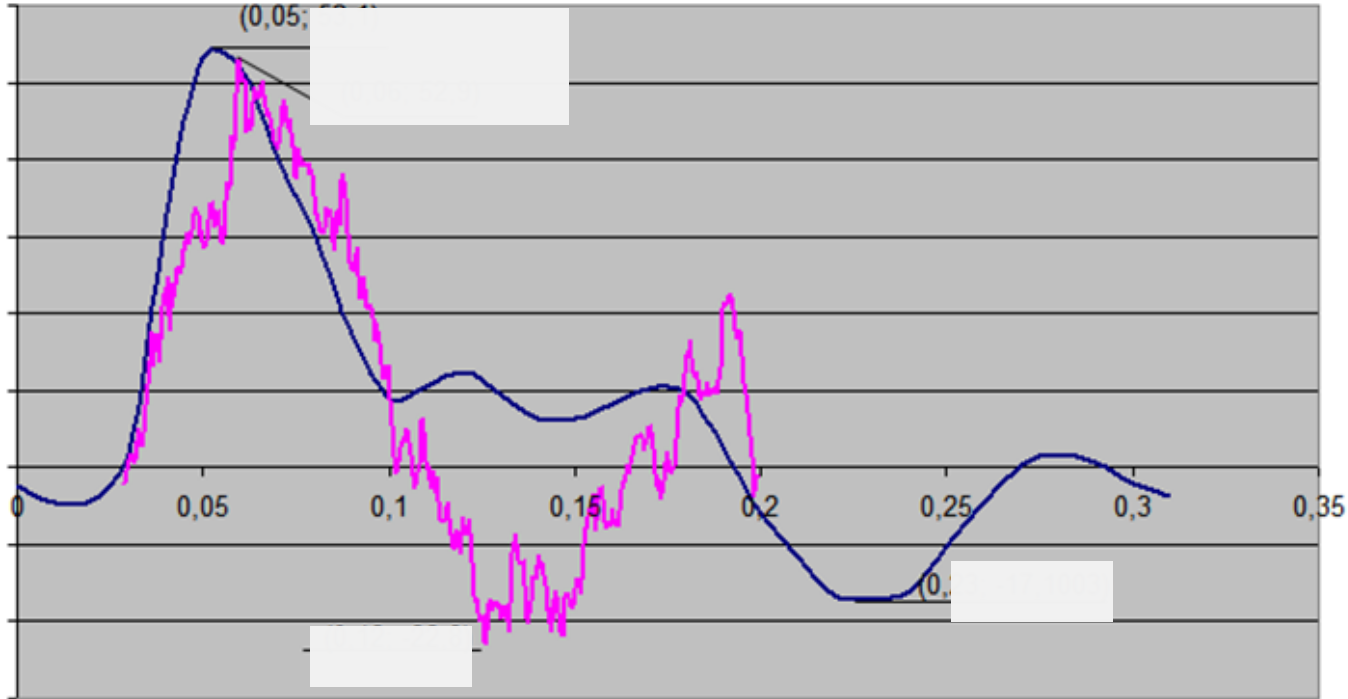
Contour Plot
Stress(vonMises, Max)

Model info: model32
Result: I:/Waterplane/run32/model32A001
Loadcase 1 : Time = 0.0000e+000
Frame 1



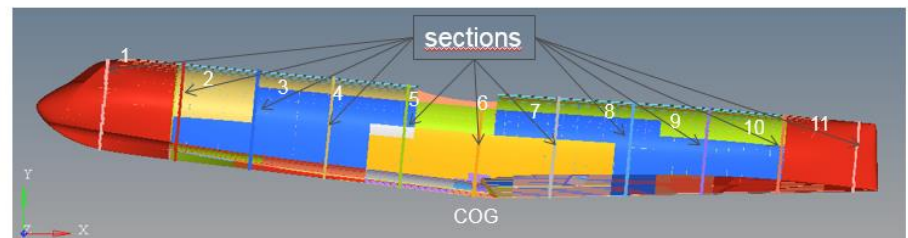
Due to multidomain approach simulation time reduced from 10 to 2 weeks

Comparison to measurements. Moments over one period of wave



Blue: landing test measurements

Lila: Radioss simulations

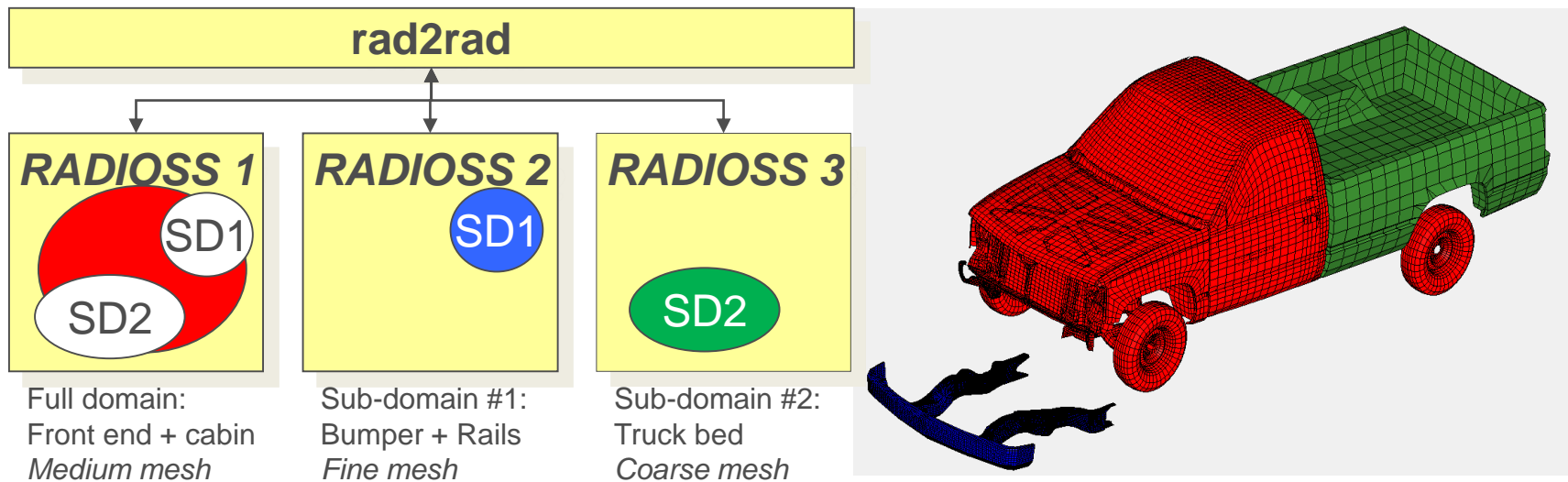


Agenda

1. What is Radioss Explicit Solver
2. Material Laws and Rupture Criteria
3. Fluid Structure interaction
4. Multi-Domain
5. Scalability / Repeatability
6. Advanced Mass Scaling
7. Example: drop test on a composite glass plate

RADIOSS - Multi-Domain

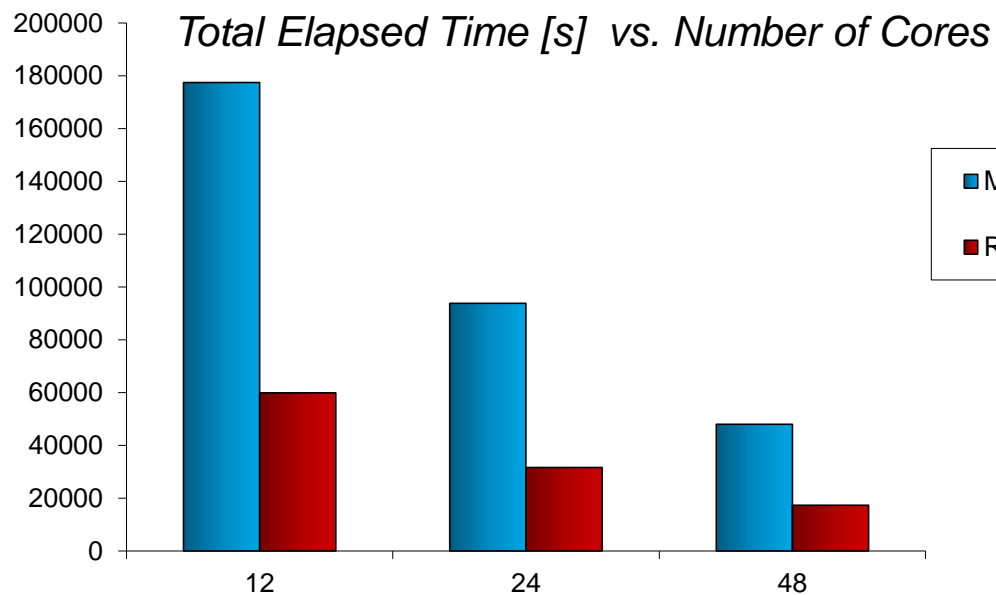
- Each domain is computed as a distinct model using its own time step staying on sync by a master RADIOSS process
- Force and momentum between domains are transferred by the master RADIOSS process insuring equilibrium and stability at sync times
- Only one domain is computed at a time



- *No limitation in term on number of domains*
- ***In case of two domains a single input is used and RADIOSS creates automatically the dedicated input decks***

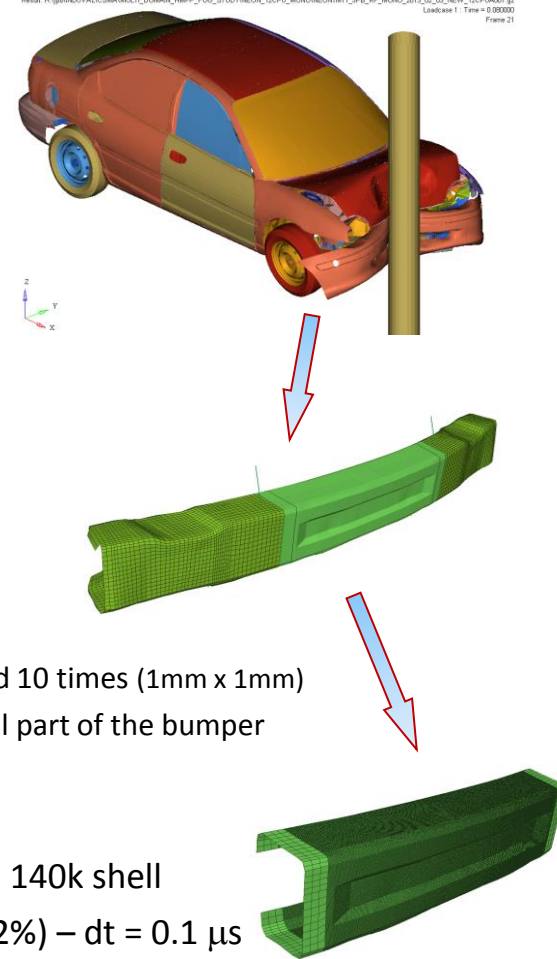
RADIOSS – Multi-Domain

- **NEON** model – pole **1.2M element model**



Speed up ratio 2.7

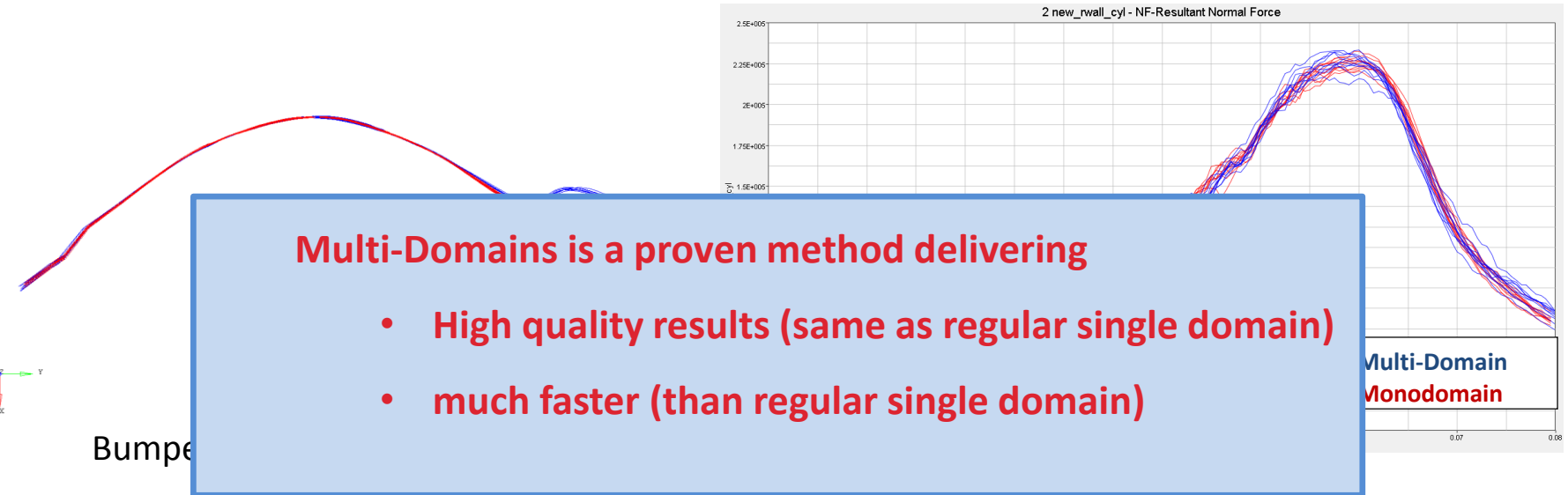
Result: H:\p\INDUVAL\CSMA\MULTI_DOMAIN_HMPP_STEEL\NEON_ICPU_MONO\NEON\M1_IPIL_IP_MOKO_2013_02_02_NEW_ICPU
 Model info: NEON\M1_IPIL_IP_MOKO_2013_02_02_NEW_ICPU
 Link case 1: Time = 0.00000
 Frame 21



RADIOSS – Multi-Domain

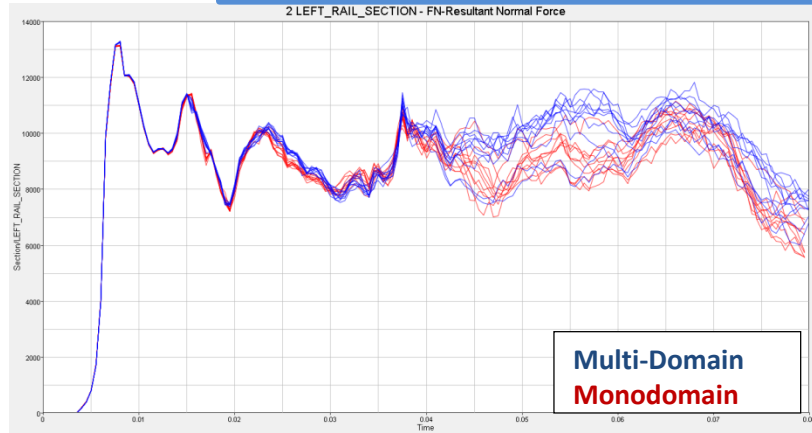
- Multi-Domain v. Monodomain Robustness Analysis

- 1 μm random noise by seed increment of 0.1 from 0.0 to 0.9

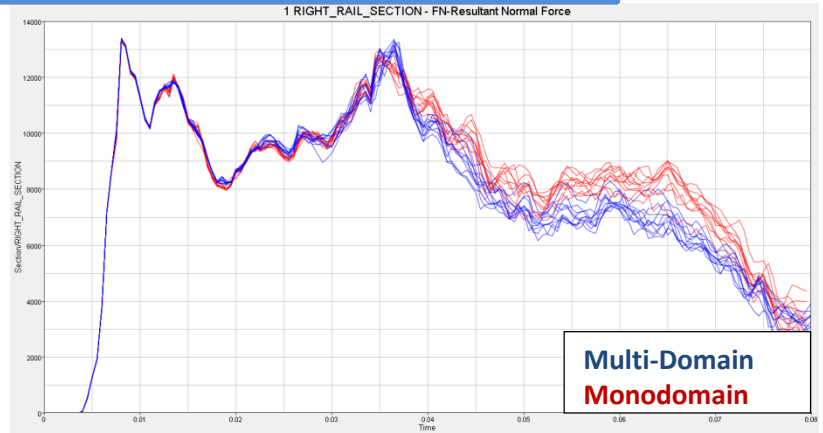


Multi-Domains is a proven method delivering

- High quality results (same as regular single domain)**
- much faster (than regular single domain)**



Left Rail Section forces



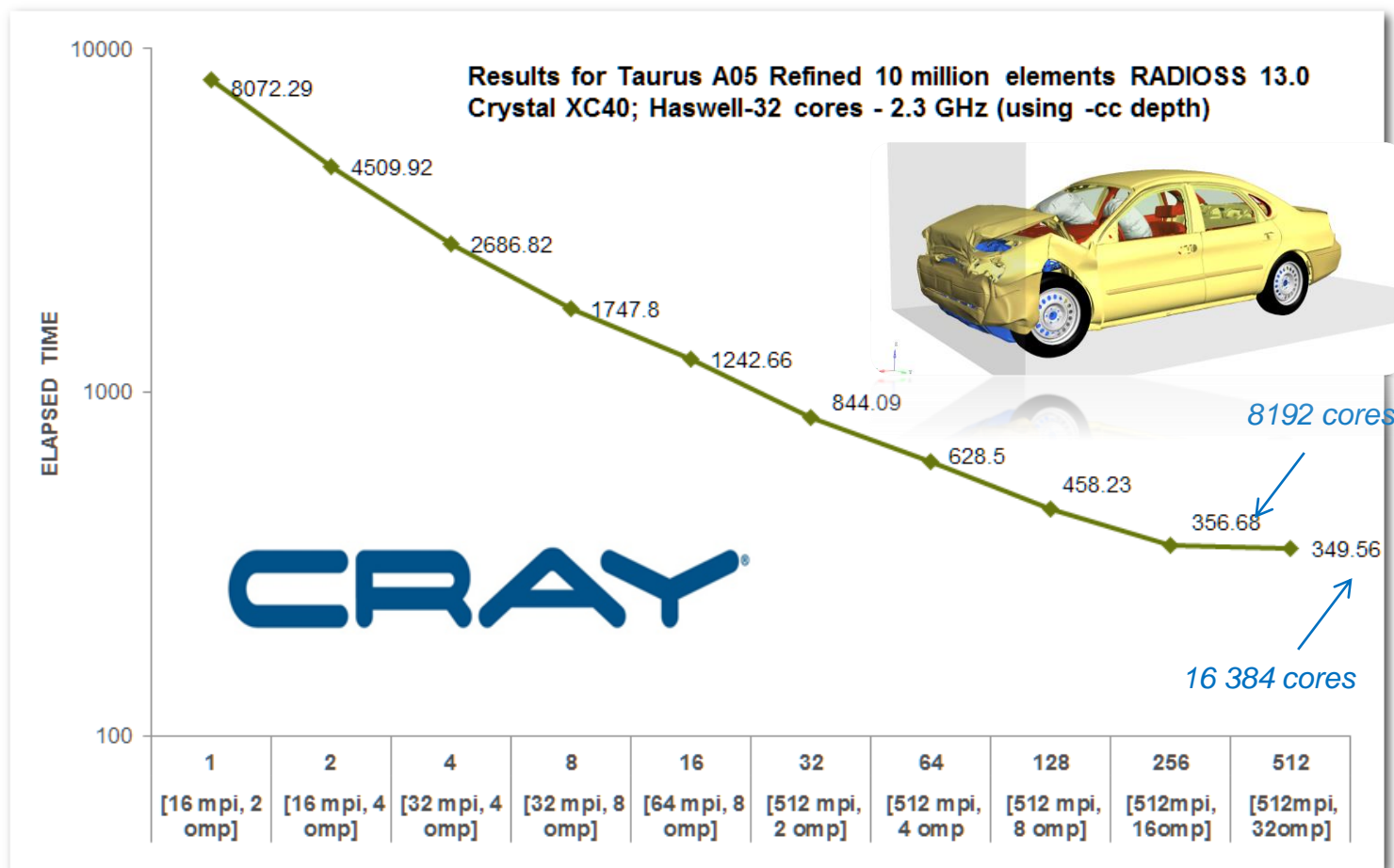
Right Rail Section forces

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- 6. Advanced Mass Scaling**
- 7. Example: drop test on a composite glass plate**

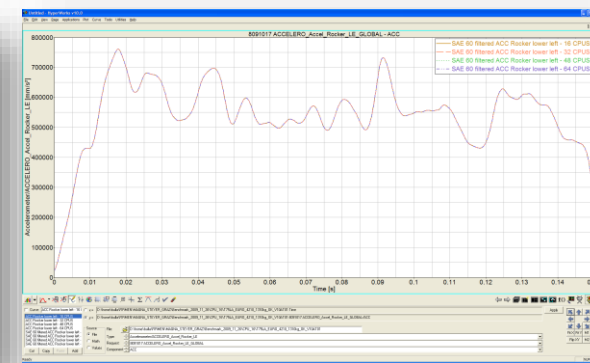
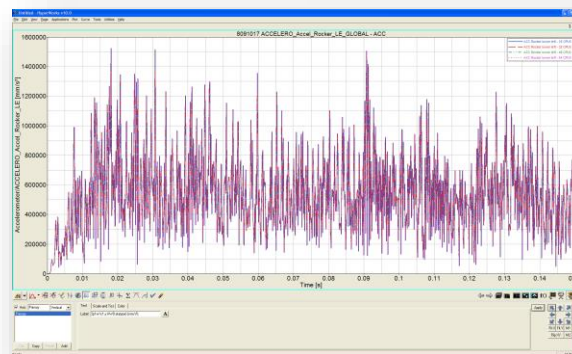
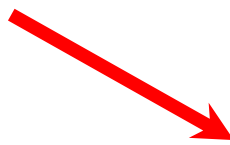
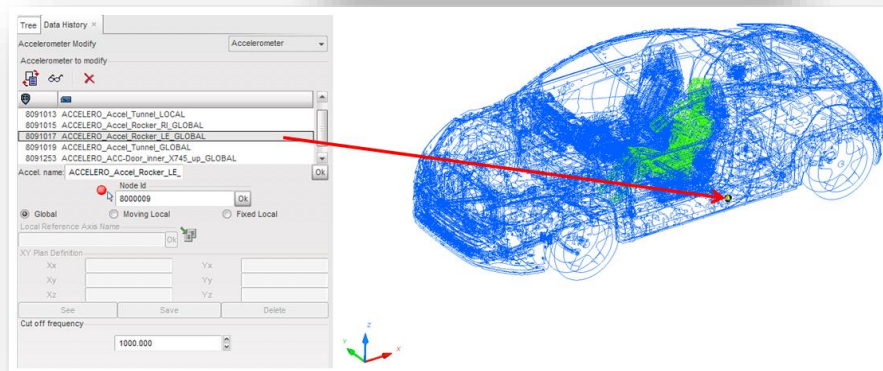
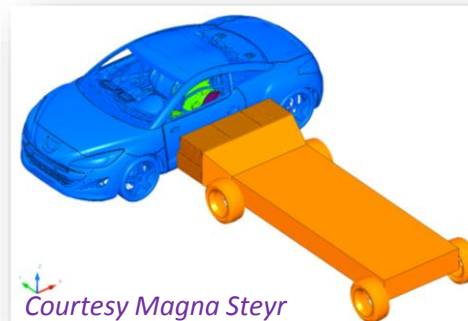
RADIOSS: Leading Scalability in crash

- Scalability** **10 Million Elements RADIOSS V13.0**



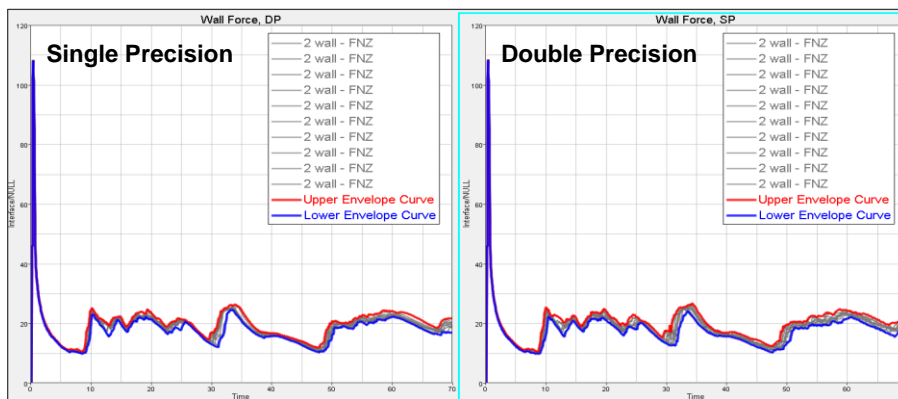
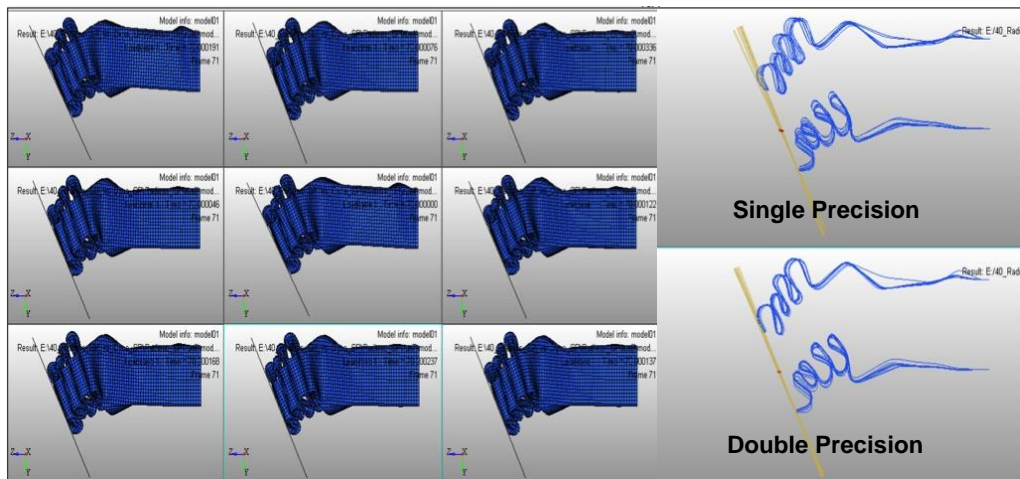
RADIOSS – Unique solution with Full Repeatability

- Full model with dummy and airbag
1.5 M elts
- Runs on 16, 32, 48 & 64 cores
- Accelerometer No.:8091017 (Rocker Lower Left)
- Perfect Repeatability Independent of amount of cores



RADIOSS - Robustness and Repeatability

Numerical scattering in RADIOSS is minimized



Single precision brings 40% speed up

(RADIOSS runs with 1 e-6 random noise applied to all nodes)

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RADIOSS speed up solution Advanced Mass Scaling

- **Classical methods for raising time step**

- Increase of mass & momentum => change the kinematic energy
- All frequencies are affected

- **AMS**

- Non diagonal mass matrix

$$M^* = M + \Lambda$$

- Assembling elementary matrices
 - δ_e large enough to obtain the target time step

$$\lambda = \frac{\delta_e}{12} \begin{bmatrix} 3 & -1 & -1 & -1 \\ -1 & 3 & -1 & -1 \\ -1 & -1 & 3 & -1 \\ -1 & -1 & -1 & 3 \end{bmatrix}$$

- Added mass = zero / No change in total mass, energy & momentum
- Low frequencies are almost not affected

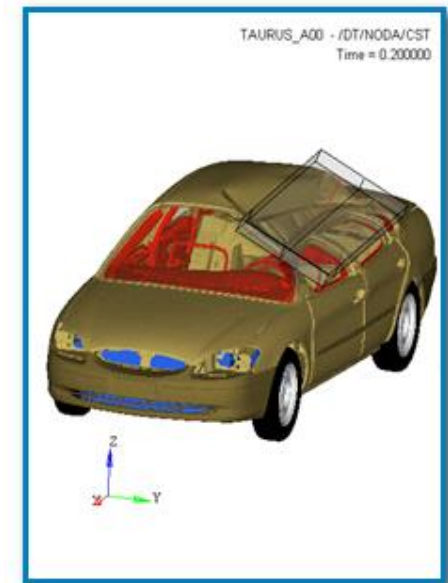


RADIOSS – Advanced Mass Scaling

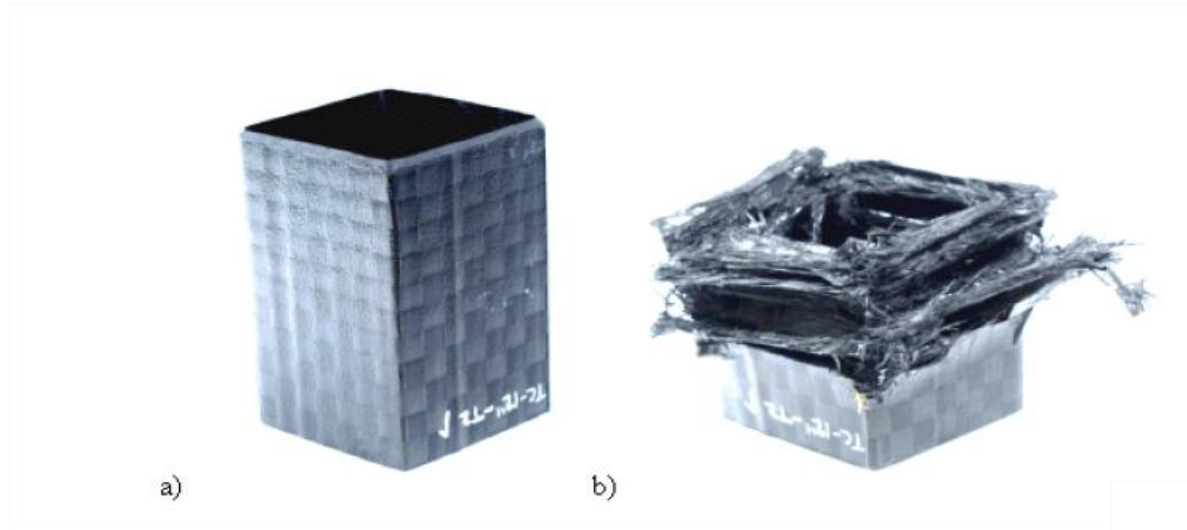
AMS

1. Competitive for quasi static simulation versus implicit
2. Efficient for manufacturing (stamping, ...)
3. Allows to stay with a “standard” time step with a fine meshed model

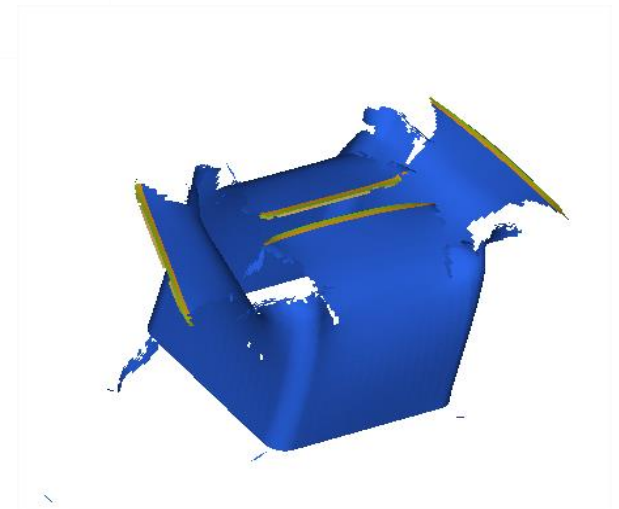
	Mass Scaling	Advanced Mass Scaling
Target time step	0,5 μ s	10 μ s
Mean time step	0,5 μ s	9,9 μ s
Nb of cycles	403187	20146
Elapsed Time (16 cores)	19.6h	4.2h
Speed-up		4.64 x



AMS example : quasi-static tube crush



- **Tube : 8 plies carbon epoxy**
- Height : 76 mm
- Side length : 63 mm
- 18545 elements (element size = 1mm)

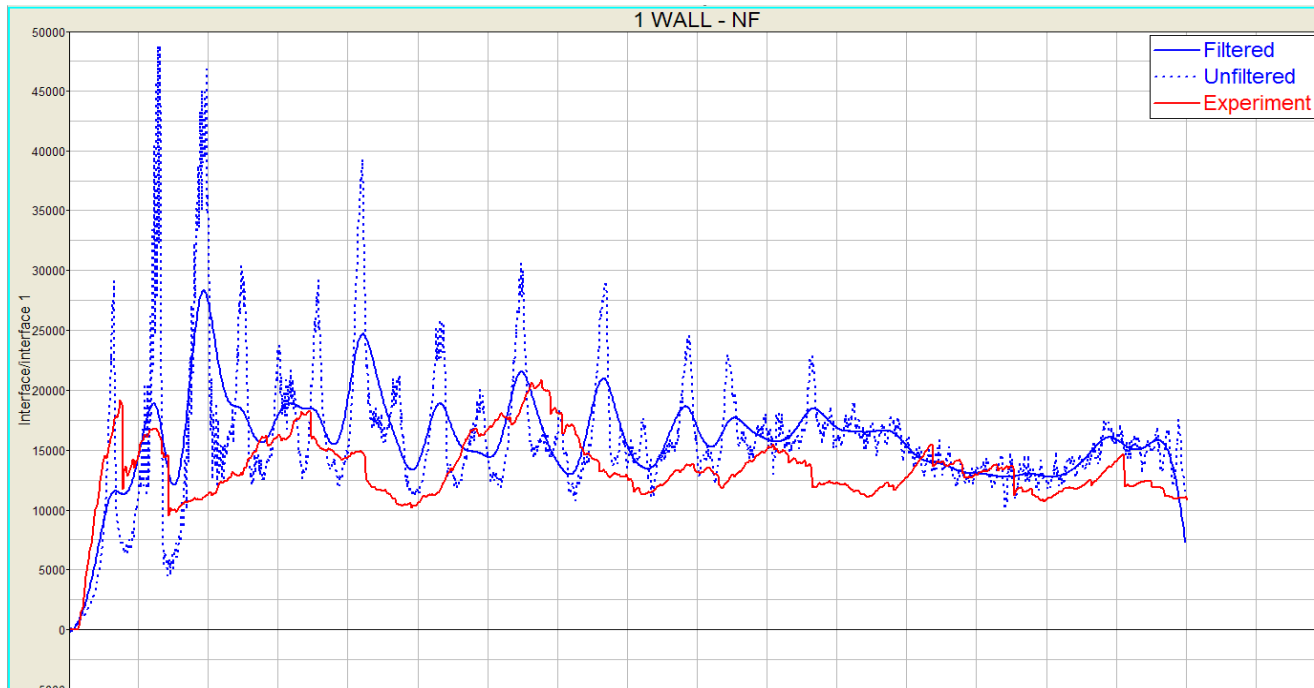


AMS : example

No AMS (mass is added for cste dt): : 10 hours

AMS, time step multiplied by 5 : 2 hours 40 minutes

AMS, time step multiplied by 10 : 2 hours 25 minutes



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Welcome to Radioss Seminar

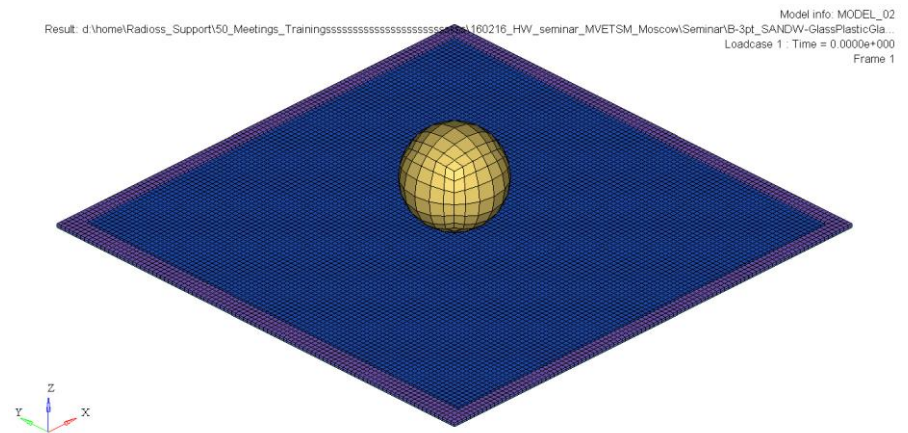
The aim of this example is to simulate failure and crack propagation into glass composite structure

Discussed:

- Definition of elasto-plastic material for the plate
- Finite element properties of shell
- Rigid wall definition
- Boundary conditions
- Simulation set up
- Post processing of results

HW programs used:

- Hypercrash for model set up
- Radioss for simulation
- Hyperview for postprocessing of results





Thank you for your attention

